

Advanced Heading and RTK Positioning

- Extremely accurate heading with long baselines
- Multi-frequency position, dualfrequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in- class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages





Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vector H328 is our most advanced GNSS heading and positioning board.

The Vector H328 utilizes dual antenna ports to create a series of additional capabilities to Eclipse™ Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

Scalable Solutions

With the Vector H328, positioning is scalable and field upgradeable with all Hemisphere software and service options. Utilize the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels available via Atlas correction service.

Ease of Migration

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.



precision@hgnss.com www.hgnss.com **GNSS Receiver Specifications**

Multi-Frequency GPS, GLONASS, BeiDou, Receiver Type:

Galileo, QZSS, and Atlas Signals Received: GPS L1CA/L1P/L1C/L2P/L2C/L5

GLONASS G1/G2, P1/P2 BeiDou B1/B2/B3 GALILEO E1BC/E5a/E5b

QZSS L1CA/L2C/L5/L1C Atlas

1059 Channels: GPS Sensitivity: -142 dBm

SBAS Tracking: 3-channel, parallel tracking

Update Rate: 10 Hz standard, 1 Hz or 20 Hz optional (with

activation) Timing (1PPS) Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) Warm Start: 30 s typical (almanac and RTC) Hot Start: 10 s typical (almanac, RTC and position)

Heading Fix: 10 s typical (Hot Start)

Antenna Input

50 Ω Impedance:

Maximum Speed: 1,850 kph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

RMS (67%) 2DRMS (95%) Position: Autonomous, no SA: 1 1.2 m 2.5 m SBAS: 2 $0.3 \, \text{m}$ $0.6 \, \mathrm{m}$ Atlas H10 (L-band): 1,3 0.04 m $0.08 \, m$

Atlas H30 (L-band): 1,3 0.15 m 0.3 m Atlas Basic (L-band): 1,3 0.50 m 1.0 m 8 mm + 1 ppm

15 mm + 2 ppm Heading (RMS): 0.16° rms @ 0.5 m antenna separation 0.08° rms @ 1.0 m antenna separation

0.04° rms @ 2.0 m antenna separation 0.02° rms @ 5.0 m antenna separation

Pitch/Roll (RMS):

Heave (RMS): 30 cm rms (DGPS), 5 cm rms (RTK)

L-Band Receiver Specifications

Single Channel Receiver Type: 1525 to 1560 MHz Channels: -130 dBm Sensitivity: Channel Spacing: 5.0 kHz

Manual and Automatic Satellite Selection: Reacquisition Time: 15 seconds (typical)

Communications

3 x full-duplex

(1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow control)

1 x USB Device

1 x Ethernet 10/100Mbps 2 x CAN (NMEA2000, ISO 11783)

1 x SPI Interface Level: 3.3V CMOS 4800 - 115200 Baud Rates:

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

Format, RTCM v2.3, RTCM v3.2, CMR, CMR+

Data I/O Protocol: NMEA 0183, Crescent binary 3

Timing Output: 1PPS, CMOS, active high, rising edge sync, 10

 $k\Omega$, 10 pF load

Event Marker Input: CMOS, active low, falling edge sync, $10 \text{ k}\Omega$, 10

pF load

Power

Input Voltage: 3.3 VDC +/- 5% 2.0 W nominal GPS (L1) Power Consumption:

2.7 W nominal GPS (L1/L2) and GLONASS

(G1/G2)

3.8 W nominal All Signals + L-band Current Consumption:

0.61 A nominal GPS (L1) 0.82 A nominal GPS (L1/L2)

1.15 A nominal All Signals + L-band

5 VDC maximum

10 to 40 dB Antenna Gain Input Range:

Environmental

Protection:

Antenna Voltage:

Antenna Short Circuit

Operating Temperature: Storage Temperature:

Humidity:

Mechanical Shock:

Vibration:

EMC:

Mechanical

Dimensions:

Weight: Status Indication (LED):

Power/Data Connector:

Antenna Connectors:

Aiding Devices

Gyro:

Tilt Sensors:

 -40° C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure) EP455 Section 5.14.1 Operational (when

mounted in an enclosure with screw

mounting holes utilized) EP455 Section 5.15.1 Random

CE (IEC 60945 Emissions and Immunity) FCC Part 15, Subpart B

CISPR 22

100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in)

44 g (1.56 oz)

Power, Primary and Secondary GNSS lock, Differential lock, DGPS position,

Heading

24-pin male header 2 mm pitch 16-pin male header 2 mm pitch

MMCX, female, straight

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1

per minute for up to 3 minutes. Provide pitch, roll data and assist in fast start-up and reacquisition of heading

solution

1 Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

- 2 Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity
- 3 Hemisphere GNSS proprietary
- 4 With future firmware upgrade and activation

Authorized Distributor:

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