

Vector[™] VS-i8 Inertial Navigation System

PROFESSIONAL HIGH-PRECISION GNSS + INS RECEIVER

Vatlas[®]



Industry-Leading GNSS and INS Technology

The Hemisphere VS-i8 is a high accuracy, high precision, Inertial Navigation System (INS) product. Featuring Honeywell® proprietary sensor fusion technology, the VS-i8 leverages a powerful multi-frequency, multiconstellation, RTK-ready navigation and positioning solution for a wide variety of GNSS platforms and applications.

Full-Featured Performance

The VS-i8 combines Hemisphere's Athena RTK positioning engine, full Atlas L-band capability, and proven Honeywell IMU technology to deliver accurate time-stamped position, velocity, angular rate, linear acceleration, roll, pitch, and heading information. Featuring a lightweight compact size, the performance of the VS-i8 is ideal for marine, UAV, robotics, mapping, GIS, LiDAR, mobile mapping, and applications requiring high performance in a small package.

Key Features

- Athena GNSS engine-providing best-in-class RTK performance
- Extremely accurate dual-antenna heading
- Atlas[®] L-band capable
- Non-ITAR controlled
- 0.03° heading, 0.015° pitch and roll accuracy on a 2m baseline
- Rugged IP68 enclosure
- Onboard data logging
- SDK, ROS drivers available

GNSS Receiver Specifications

Receiver Type:	INS with Multi-Frequency GPS, GLONASS, BeiDou, Galileo, QZSS, NavIC (IRNSS), and
	Atlas L-band
Signals	GPS L1CA/L1P/L1C/L2P/L2C/L5
Received:	GLONASS G1/G2/G3, P1/P2
	BeiDou B1i/B2i/B3i/B1C/B2a/B2b/ AceBOC
	GALILEO E1BC/E5a/E5b/E6BC/ AltBOC
	QZSS L1CA/L2C/L5/L1C/L6
	Navic (IRNSS) L5
	Atlas
Channels:	1,100+
GPS Sensitivity:	-142 dBm
SBAS Tracking:	3-channel, parallel tracking
Atlas L-band Channels:	Dual-Channel ¹
Atlas Satellite Selection:	Manual and Automatic

Communications

Ports:	2x Power / Data
Interface Levels:	2x RS-422, 1x RS-232, 5V CMOS, USB,
	Ethernet, CAN ISO 11898-2
Correction I/O	NTRIP Client, Hemisphere GNSS
Protocol:	proprietary ROX format, RTCM v2.3,
	$RTCM v3.2$, CMR^2 , CMR^{+2}
Output Rate:	GNSS 10 Hz Standard / Optional 20 Hz,
	INS up to 100 Hz Standard
Timing & Event I/O:	2x Event In, Direct Quadrature
	Encoder Input, 2x PPS
Sensor Input, Optional:	Odometer (DMI)
Onboard Logging:	16 GB With USB 2.0 Access

Mechanical Dimensions³

Dimensions.	7.0 L X 0.0
	3.5 L x 2.4
Weight:	<0.5 kg (<
Status Indicators (LED):	Power, GN
Power/Data	2x Fischer
Connectors:	DBPU 104
Antenna Connectors:	2x SMA

9.0 L x 6.0 W x 6.0 H (cm) W x 2.4 H (in) (1.1 lb.) NSS, Navigation, Data Core 16 Contact A086

Environmental

Operating Temperature: -40° C to $+71^{\circ}$ C (-40° F to $+160^{\circ}$ F) Storage Temperature: -40° C to $+85^{\circ}$ C (-40° F to $+185^{\circ}$ F) Humidity: 95% non-condensing Enclosure: IP68 per IEC 60529 **Mechanical Shock:** 40g for 11 msec (MIL-STD-810G) Random 7.7g RMS 20-2000 Hz Vibration: **MTBF:** >50,000 hours, ground mobile 25°C RoHS, WEEE, FCC Part 15, ICES-003, EMC, Certifications: CISPR 32, CE Mark Compliant

Electrical

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Input Voltage: Power Consumption: Antenna Voltage Output:

9 to 36 V DC 7.5 W nominal 5 V DC maximum

With a future firmware update.

2 CMR and CMR+ do not cover proprietary messages outside of the typical standard.

3. Excludes mounting tabs.

- 4 Using dual antennas with a 2m antenna separation. Longer baselines improve heading performance. Performance shown based on Hemisphere antennas, other antenna selection may impact final performance.
- DMI pulse count aiding through direct quadrature encoder RS422 input. Motion 5 Detect and Land Vehicle Constraints improve performance for land vehicles during GNSS outgages independently of optional DMI input.
- Typical Horizontal RMS error of ~0.25% of distance traveled with no Velocity 6. Aiding source (DMI, DVL etc.).
- 7. Statistics are calculated by taking the RMS of the maximum error over multiple complete GNSS outages in a Land Vehicle application.
- Horizontal and vertical RMS errors shown are based on starting from a fixed RTK 8. solution before and after the GNSS outage. Autonomous, SBAS, and Atlas error growth will be similar, but absolute accuracy will be reduced.

GNSS Outage Performance ^{5,6,7,8}										
		Position Accuracy (RMS)		Velocity Accuracy (RMS)		Heading	Pitch & Roll			
Outage Duration	Mode	Horizontal	Vertical	Horizontal	Vertical	(RMS)⁴	(RMS)			
0 Seconds	SBAS	<0.30 m	<0.60 m	<0.015 m/s	<0.01 m/s	<0.03°	0.015°			
0 Seconds	RTK	<0.01 m	<0.025 m	<0.015 m/s	<0.01 m/s	<0.03°	0.015°			
10 Seconds	RTK	0.10 m	0.10 m	0.04 m/s	0.01 m/s	0.06°	0.015°			
30 Seconds	RTK	1.0 m	0.30 m	0.06 m/s	0.02 m/s	0.07°	0.015°			
60 Seconds	RTK	3.5 m	0.70 m	0.15 m/s	0.03 m/s	0.08°	0.015°			



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