

Eclipse[™] Vector[™] H328 GNSS OEM Board





Patlas[®]

Develop sophisticated machine control and navigation solutions in a complex world full of dynamic environments. The Vector H328 is our most advanced GNSS heading and positioning board.

The Vector H328 uses dual antenna ports to create a series of additional capabilities to Eclipse Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

Scalable Solutions

With the Vector H328, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels are available via Atlas correction service.

Ease of Migration

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

Key Features

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

GNSS Receiver Specifications

Receiver Type: Multi-Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS, and Atlas GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

> GLONASS G1/G2, P1/P2 BeiDou B1/B2/B3

GALILEO E1BC/E5a/E5b QZSS L1CA/L2C/L5/L1C

Atlas 1059

Channels: **GPS Sensitivity:** -142 dBm

SBAS Tracking: 3-channel, parallel tracking **Update Rate:** 10 Hz standard, 1 Hz or 20 Hz optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) 30 s typical (almanac and RTC) Warm Start: **Hot Start:** 10 s typical (almanac, RTC and

position)

Heading Fix: 10 s typical (Hot Start)

Antenna Input

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) Autonomous, no SA: 1 1.2 m $2.5 \, \mathrm{m}$

0.6 m SBAS: 1 $0.3 \, \mathrm{m}$ Atlas H10: 1, 3 $0.08 \, \text{m}$ $0.04 \, \text{m}$ Atlas H30: 1, 3 $0.15 \, \text{m}$ $0.3 \, \mathrm{m}$ Atlas Basic: 1,3 1.0 m $0.50 \, \text{m}$

RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.16° rms @ 0.5 m antenna

separation

0.08° rms @ 1.0 m antenna

separation

0.04° rms @ 2.0 m antenna

separation

0.02° rms @ 5.0 m antenna

separation

Pitch/Roll (RMS): 10

30 cm rms (DGNSS), 5 cm rms (RTK) Heave (RMS): 1

L-Band Receiver Specifications

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

- Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity
- Hemisphere GNSS proprietary
- With future firmware upgrade and activation
- CMR and CMR+ do not cover proprietary messages outside of the typical standard



Communications

3 x full-duplex (1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)

1 x USB Device

1 x Ethernet 10/100Mbps

2 x CAN (NMEA2000, ISO 11783)

1 x SPI 3.3V CMOS

Interface Level: 4800 - 115200 **Baud Rates:**

Correction I/O Protocol: Hemisphere GNSS proprietary ROX format, RTCM v2.3, RTCM v3.2,

CMR⁵, CMR+⁵ NMEA 0183, Crescent binary ⁵ 1 PPS, CMOS, active high, rising Data I/O Protocol: **Timing Output:** edge sync, $10 \text{ k}\Omega$, 10 pF load

Event Marker Input: CMOS, active low, falling edge

sync, $10 \text{ k}\Omega$, 10 pF load

Power

Input Voltage: 3.3 VDC +/- 5%

Power Consumption:

2.0 W nominal GPS (L1) 2.7 W nominal GPS (L1/L2) and GLONASS (G1/G2)

3.8 W nominal All Signals + L-band 0.61 A nominal GPS (L1) 0.82 A nominal GPS (L1/L2)

Current Consumption:

1.15 A nominal All Signals + L-band

Antenna Voltage: 5 VDC maximum Antenna Short Circuit

Protection: Antenna Gain Input

Range:

10 to 40 dB

Yes

Environmental

Operating Temperature:

Storage Temperature:

Humidity:

 -40° C to +85°C (-40°F to +185°F -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and EMC:

Immunity) FCC Part 15, Subpart B

CISPR 22

Mechanical

100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in) 44 g (1.56 oz) **Dimensions:**

Weight:

Status Indications (LED): Power, Primary and Secondary GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data Connector:

24-pin male header 2 mm pitch 16-pin male header 2 mm pitch

Antenna Connectors: MMCX, female, straight

Aiding Devices Gyro:

Provides smooth and fast heading reacquisition. During loss of GNSS

signals heading stability is degraded by < 1° per minute for up to 3

minutes.

Provide pitch, roll data and assist in Tilt Sensors:

fast start-up and reacquisition of

heading solution

Hemisphere GNSS

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