

## Vector<sup>™</sup> V102 GPS Smart Antenna

## GENERAL NAVIGATION HEADING AND POSITIONING COMPASS





Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V102 GPS compass. The Vector V102 uses SBAS for differential GPS positioning allowing Hemisphere GNSS to provide a highly effective heading and position based smart antenna that out rank any fluxgate compasses.

The rugged low profile enclosure combined with Hemisphere GNSS' Crescent® Vector OEM technology gives portability and simple installation. The compass - measuring less than half-meter length - mounts easily to a flat surface or pole. The stability and maintenance- free design of the Vector V102 provides simple integration into autopilots, chart plotters, and AIS systems.

## **Key Features**

- Provides heading, positioning, heave, roll, and pitch
- Excellent in-band and out-of-band interference rejection
- 0.75 degree heading accuracy in an amazingly small form factor
- Differential positioning accuracy of 1.0 m, 95% of the time
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Accurate heading up to 3 minutes during GNSS outages

**GPS Receiver Specifications** 

**Receiver Type:** Vector GPS L1 Compass

Signals Received: GPS

**Channels:** Two 12-channel, parallel tracking

(Two 10-channel when tracking SBAS)

GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking
Update Rate: 10 Hz standard, 20 Hz optional

**Rate of Turn:** 90°/s maximum

Compass Safe

**Distance:** 30 cm <sup>4</sup>

Cold Start: 60 s (no almanac or RTC)
Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

**Heading Fix:** 10 s typical (valid position)

Maximum Speed: 1,850 mph (999 kts)

Maximum

**Altitude:** 18,288 m (60,000 ft)

Differential

**Options:** SBAS

Accuracy

Position: RMS (67%)

Autonomous,

no SA: 1 1.2 m SBAS: 2 0.5 m Heading (RMS): 0.75° Pitch/Roll (RMS): 1.5° Heave (RMS): 30 cm<sup>3</sup>

**Communications** 

Ports: 2 full-duplex RS232 Baud Rates: 4800 - 115200

Correction I/O

Protocol: RTCM SC-104

Data I/O Protocol: NMEA 0183, NMEA 2000, Hemisphere

Crescent binary 5

**Power** 

**Input Voltage:** 6 to 36 VDC

Power Consumption:3.0 W nominal (GPS L1)Current Consumption:0.25 A nominal (GPS L1)Power Isolation:Isolated to enclosure

**Reverse Polarity** 

**Protection:** Yes

**Environmental** 

Operating

Temperature:  $-30^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  (-22°F to  $+158^{\circ}\text{F}$ ) Storage Temperature:  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  (-40°F to  $+185^{\circ}\text{F}$ )

**Humidity:** 

95% non-condensing EP455 Section 5.14.1

Mechanical Shock: Vibration: EMC:

EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and

Immunity) FCC Part 15, Subpart B,

CISPR22

Mechanical

**Dimensions:** 41.7 L x 15.8 W x 6.9 H (cm) 16.4 L x 6.2 W x 2.7 H (in)

**Weight:** 1.5 kg (3.3 lbs.)

**Status Indications** 

(LED): Power, GNSS Lock, Heading

Power/Data

**Connector:** 12-pin, Female, IP67

**Aiding Devices** 

**Gyro:** Provides smooth heading, fast

heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS

has occurred

**Tilt Sensors:** Provide pitch and roll data and

assist in fast start-up and

reacquisition of heading solution

Hemisphere GNSS proprietary



**Hemisphere GNSS** 

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Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

<sup>3.</sup> Based on a 40 second time constant

<sup>4.</sup> This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation